

VINDULA JAYAWARDANA

PERSONAL INFORMATION

Cambridge, United States
✉ vindula@mit.edu
🌐 www.vindulaj.com
in [in/vindulajayawardana](https://www.linkedin.com/in/vindulajayawardana)

RESEARCH INTERESTS

I am broadly interested in *learning-enabled autonomy*. In light of this, I am interested in making multi-agent reinforcement learning seamlessly generalize across problem variations (solving Contextual MDPs). Real-world application-wise, I am interested in learning-enabled planning for autonomous vehicles under problem variations. In the past, I have also worked on mathematical programming for on-demand high-capacity ride-sharing systems and natural language processing for information extraction.

EDUCATION

Massachusetts Institute of Technology, Cambridge, USA *Sep 2019-May 2025*
Ph.D. Electrical Engineering and Computer Science (GPA: 4.9/5.0)

Massachusetts Institute of Technology, Cambridge, USA *Sep 2019-Sep 2022*
M.S. Electrical Engineering and Computer Science (GPA: 4.9/5.0)
Thesis: *An Invisible Issue of Task Underspecification in Deep Reinforcement Learning Evaluations*

University of Moratuwa, Colombo, Sri Lanka *Mar 2014 -Dec 2017*
B.S. Computer Science and Engineering (GPA: 4.08/4.2)
Thesis: *Ontology-based Legal Information Extraction*

RELEVANT EXPERIENCE

Massachusetts Institute of Technology, Cambridge, USA *Sep 2019-May 2025*
Ph.D. Candidate

- Working with Prof. Cathy Wu at Laboratory for Information and Decision Systems.
- Research on improving robustness and generalization in reinforcement learning, specifically when solving Contextual MDPs [1, 3, R1, F1, W1].
- Model and build large-scale traffic simulations that span over ten major US cities and nearly three million traffic scenarios for impact assessment of cooperative eco-driving [R1, 7, W1].
- Conduct studies validating the efficacy of reinforcement learning for real-world problems, including large-scale eco-driving [4, R1], socially compatible driving [5], traffic smoothing [2, 6], and combinatorial optimizations [F2].

Toyota Motor North America, Mountain View, USA *June 2023-Aug 2023*
Research Intern

- Worked with Dr. Yashar Farid and Mr. Kentaro Oguchi in the Advance Development and Planning group at Toyota InfoTech Labs.
- Improved generalization in multi-agent reinforcement learning across problem variations by combining model-based policies with learning-based policies. Paper published at ICRA 2024 [1].
- Conducted experiments to validate the effectiveness of the proposed method on eco-driving across 600 signalized intersections and 1200 traffic scenarios [1, W1].
- Proposed a hierarchical policy architecture aiming for continual learning for eco-driving across signalized intersections. The patent is in submission [R2].

University of Moratuwa, Colombo, Sri Lanka *Jan 2018-July 2019*
Research Assistant

- Worked with Dr. Shehan Perera and Dr. Uthayasankar Thayasivam.
- Conducted ride-sharing simulations with integer programming for request-driver matching.
- Conducted ride-pooling with meeting points simulations based on integer programming formulations for request-driver-meeting point matching.
- Analyzed the optimality gaps between heuristic methods and optimal methods for ride-pooling with meeting points problem [9].

Digital Mobility Solutions Lanka, Colombo, Sri Lanka *Jan 2018-July 2019*
Consultant Researcher

- Built numerical simulations of ride-sharing in major Sri Lankan cities based on real-world data.
- Evaluated the effectiveness of ride-sharing in select cities with large-scale numerical simulations.

Research Intern

- Worked with Prof. Samitha Samaranyake.
- Built an open source ride pooling simulator in C++ for large-scale ride pooling with integer programming based driver-passenger matching.
- Formulated Integer programming models for ride pooling with meeting points problem [9].

WSO2, Colombo, Sri Lanka

July 2016-Dec 2016

Software Engineering Intern

- Developed an open-source library Charon for SCIM 2.0 support following IETF specifications.
- Integrated SCIM 2.0 support for the WSO2 Identity server.

- WORK IN REVIEW [R1] V. Jayawardana, B. Freydt, A. Qu, C. Hickert, E. Sanchez, C. Tang, S.Chandrasiri, M. Taylor, B.Leonard, C. Wu, *Mitigating metropolitan vehicular carbon emissions with semi-autonomous vehicles using deep reinforcement learning*, In peer-review stage (Nature).
- [R2] V. Jayawardana, Y. Farid, K. Oguchi. *Systems and methods for vehicles navigating roads using a control model trained with residual policies*, In review (U.S patent).
- [R3] E. Sanchez, C. Tang, V. Jayawardana, and C. Wu, "Learning surrogates for diverse emission models," In review (Journal of Machine Learning Research)
- [R4] Y. Kim, V. Jayawardana, S. Samaranyake, *Learning augmented vehicle dispatching with slack times for high-capacity ride-pooling*, In review (TR-C).
- SELECTED PUBLICATIONS [1] V. Jayawardana, S. Li, C. Wu, Y. Farid, K. Oguchi. *Generalizing cooperative eco-driving via multi-residual task learning*, IEEE International Conference on Robotics and Automation (ICRA) 2024.
- [2] D. Suo*, V. Jayawardana*, C. Wu, *Model-free learning corridor clearance: A near term deployment perspective*, IEEE Transactions on Intelligent Transportation Systems (T-ITS) 2023. * **equal contribution**.
- [3] V. Jayawardana, C. Tang, S. Li, D. Suo, C. Wu. *The impact of task underspecification in evaluating deep reinforcement learning*, Advances in Neural Information Processing Systems (NeurIPS) 2022.
- [4] V. Jayawardana, C. Wu. *Learning eco-driving strategies at signalized intersections*, European control Conference (ECC) 2022. **MIT News Spotlight, NPR, and Tech Crunch featured**.
- [5] S. Jayawardana, V. Jayawardana*, K.Vidanage, C. Wu*. *Multi-behavior learning for socially compatible autonomous driving*, IEEE International Conference on Intelligent Transportation Systems (ITSC) 2023. * **equal supervision**
- [6] D. Zhuang, Y. Huang, V. Jayawardana, J. Zhao, D. Suo, and C. Wu, *The braess paradox in dynamic traffic*, IEEE International Conference on Intelligent Transportation Systems (ITSC) 2022.
- [7] Qu, A. Valiveru, C. Tang, V. Jayawardana, B. Freydt, and C. Wu, *What is a typical signalized intersection in a city?* Transportation Research Board (TRB) 2022.
- [8] V. Jayawardana, A. Landler, C. Wu. *Mixed autonomous supervision in traffic signal control*, IEEE International Conference on Intelligent Transportation Systems (ITSC) 2021.
- [9] M. Mounesan, V. Jayawardana, Y. Wu, S. Samaranyake, H. T. Vo, *Fleet management for ride-pooling with meeting points at scale: A case study in the five boroughs of New York City*, 2021.
- * More on [Google Scholar](#).
- WORK IN PREPARATIONS [F1] V. Jayawardana, C. Wu. *Learning-guided calibrations of microscopic traffic simulators*, In preparation (NeurIPS 2024).
- [F2] V. Jayawardana, Z. Yan, A. Qu, B. Freydt, C. Wu. *ScenarioGym : Three million traffic scenarios for benchmarking contextual and adaptive reinforcement learning*, In preparation (NeurIPS 2024).
- [F3] J. Cho, V. Jayawardana, C. Wu. *Model-based transfer learning for contextual reinforcement learning*, In preparation (NeurIPS 2024).
- WORKSHOP PAPERS [W1] V. Jayawardana, S. Li, C. Wu, Y. Farid, K. Oguchi. *Robust Driving Across Scenarios via Multi-residual Task Learning*, In Generalization in Planning workshop at Advances in Neural Information Processing Systems (NeurIPS) 2023 and Machine Learning for Autonomous Driving Symposium 2023.
- [W2] V. Jayawardana, C. Wu. *Reinforcement Learning for Eco-Lagrangian Control at Intersections*, In Robotics for Climate Change workshop at IEEE International Conference on Robotics and Automation (ICRA) 2022.

SKILLS AND PROJECTS	<p>Technical Skills: Python (Numpy, PyTorch), C++, Java, C#, JavaScript/CSS/HTML, SQL, Bash, Linux, VSCode, Latex, Gurobi, Mosek, SUMO</p> <p>Research Skills: Reinforcement learning, planning for autonomous vehicles, numerical simulations, intelligent transportation systems, machine learning, control theory, optimizations, traffic engineering, and data analytics.</p> <p>Selected Research Projects: Greenwave (AI-driven eco-driving) - Project lead for 14-member team</p> <p>Open Source Projects</p> <p>Open Ridepool Simulator - Co-main contributor</p> <p>SCIM 2.0 Compliance Test Suite - Main contributor (Google Summer of Code 2017)</p> <p>Charon 3.0: SCIM 2.0 Implementation - Main contributor</p>																																				
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TEACHING

Teaching Assistant

1.041/1.200 - Transportation: Foundations and Methods (**MIT EECS Teaching Excellence Award**)

MIT Fall 2020, 2021

CS2022 - Data Structures and Algorithms	<i>UoM Spring 2019</i>
CS4622 - Machine Learning	<i>UoM Fall 2018</i>
CS3042 - Database Systems	<i>UoM Fall 2018</i>
CS2052 - Computer Architecture	<i>UoM Spring 2018</i>
CS2062 - Object Oriented Software Development	<i>UoM Spring 2018</i>
CS3962 - Research and Report Writing	<i>UoM Fall 2017</i>

MENTORSHIP

Graduate Students

Jessica Ding: MIT

- Co-authoring a paper on residual transfer learning for traffic control.
- Baptiste Freydt*: ETH Zurich (Now: software engineer)
- Co-authored a paper on large-scale eco-driving using deep reinforcement learning [R1].

Undergraduates

Anna Landler: MIT (Now: software engineer at Crusoe)

- Co-authored paper on autonomous traffic signal supervision [8].

Catherine Tang: MIT (Now: sophomore at MIT)

- Co-authored papers on task underspecification in deep reinforcement learning [3].

Anirudh Valiveru: MIT (Now: sophomore at MIT)

- Co-authored paper on data processing pipeline for open street maps.

Ammar Fayad: MIT (Now: junior at MIT)

Jiaxin He: Vanderbilt University (Now: master student at UC San Diego)

- Co-authored a paper on large-scale eco-driving using deep reinforcement learning [R1].

Sunera Chandrasiri: University of Moratuwa (Now: co-founder of iXD Labs)

- Co-authored a paper on large-scale eco-driving using deep reinforcement learning [R1].

Sanjula Jayawardana: University of Westminster (Now: software engineer at IFS)

- Co-authored a paper on socially compatible autonomous driving [5].

MEDIA

MIT News **spotlight**: [On the road to cleaner, greener, and faster driving](#)

Techcrunch: [Perceptron: Risky teleoperation, Rocket League simulation, and zoologist multiplication](#)

National Public Radio (NPR): [Green Driving](#)

ADAS & Autonomous Vehicle International Magazine: [A greener way to negotiate traffic lights](#)